## Assignment VI, PHYS 412 (MAP) Fall 2014 Due 10/03/14 at start of class

1. Write the following equations in index notation. The tilde symbol above a variable (e.g.  $\widetilde{A}$ ) indicates a matrix. (All of the equations below should be well-defined).

a) 
$$\vec{f} = \vec{a} + \vec{b} \times \vec{c}$$

b) 
$$(\vec{a} \times \vec{b}) \times \vec{c} = (\vec{f} \cdot \vec{g}) |\vec{h}|^2 \vec{k}$$

c) 
$$\widetilde{A}\vec{x} - (\vec{y} \times \vec{z}) = \vec{b}$$

d) 
$$\vec{\nabla}\phi + \vec{\nabla} \times \vec{a} = (\vec{\nabla} \cdot \vec{b})\vec{c}$$

e) 
$$(\nabla^2 \phi) \vec{a} + \widetilde{B} \vec{c} = \vec{d} \times \vec{f}$$

f) 
$$\frac{\partial^2 \vec{u}}{\partial t^2} = |\vec{v}|^2 \nabla^2 \vec{u}$$

g) 
$$\frac{-\hbar^2}{2m} \nabla^2 \Psi + V \Psi = i\hbar \frac{\partial \Psi}{\partial t}$$

h) 
$$\vec{u} + (\vec{a} \cdot \vec{b})\vec{v} = |\vec{a}|^2(\vec{b} \cdot \vec{v})\vec{a}$$

2. Use index notation to demonstrate the following:

a) 
$$\vec{a} \times (\vec{b} \times \vec{c}) = \vec{b}(\vec{a} \cdot \vec{c}) - \vec{c}(\vec{a} \cdot \vec{b})$$

b) 
$$\vec{\nabla} \cdot (\vec{a} \times \vec{b}) = \vec{b} \cdot (\vec{\nabla} \times \vec{a}) - \vec{a} \cdot (\vec{\nabla} \times \vec{b})$$

c) 
$$\vec{\nabla} \times (\vec{\nabla}\phi) = 0$$

d) 
$$\vec{\nabla} \times (\vec{\nabla} \times \vec{a}) = \vec{\nabla}(\vec{\nabla} \cdot \vec{a}) - \nabla^2 \vec{a}$$

3. The Helmholtz theorem tells us that any vector  $\vec{F}$  can be written as the negative gradient of a scalar field plus the curl of a vector field. i.e.:

$$\vec{F} = -\vec{\nabla}V + \vec{\nabla} \times \vec{E}$$

- a) Rewrite the above vector equation in index notation.
- b) Manipulate the expression in part (a) to show that  $\vec{\nabla} \times \vec{F} = \vec{\nabla}(\vec{\nabla} \cdot \vec{E}) \nabla^2 \vec{E}$ . (This doesn't mean just referencing some source that argues that this is true; it means manipulating the index notation to clearly progress from the expression in part (a) to something equivalent to the above in index notation).

MORE ON BACK!!!

- 4. Use index notation to simplify / rewrite the following to the number of terms specified. (Let  $\phi$  be an arbitrary scalar function and  $\vec{a}$  be an arbitrary vector function):
  - a)  $\vec{\nabla} \times (\phi \vec{\nabla} \phi)$  (when simplified, this can be written as a single term).
  - b)  $\vec{\nabla} \cdot (\phi \vec{\nabla} \phi)$  (when rewritten, this should have two terms).
  - c)  $\vec{\nabla} \times (\phi \vec{a})$  (when rewritten, this should have two terms).
- 5. Simplify the following expressions:
  - a)  $\delta_{ij}\delta_{ij}$
  - b)  $\delta_{ij}\delta_{jk}\delta_{ki}$
  - c)  $\epsilon_{ijk}\epsilon_{mjk}$
  - d)  $\epsilon_{ijk}\epsilon_{ijk}$
  - e)  $\delta_{ij}\epsilon_{jkm}$
- 6. Let  $\hat{r}(t) \cdot \hat{r}(t) = 1$ . Differentiate both sides of the equation. Based on your result, what is the geometrical relationship between  $\hat{r}$  and  $\dot{\hat{r}}$  (the time derivative of  $\hat{r}$ )? (This should teach you or remind you about a property of polar coordinates. If you have no idea what I'm talking about, don't worry.)
- 7. The force on a charge q moving with velocity  $\vec{v} = \frac{d\vec{r}}{dt}$  in a magnetic field  $\vec{B}$  is  $\vec{F} = q(\vec{v} \times \vec{B})$ . Since  $\vec{\nabla} \cdot \vec{B} = 0$ , we can write  $\vec{B}$  as  $\vec{B} = \vec{\nabla} \times \vec{A}$  where  $\vec{A}$  (called the vector potential) is a vector function of x, y, z, t. If the position vector  $\vec{r} = x\hat{x} + y\hat{y} + z\hat{z}$  of the charge q is a function of time t show that  $\frac{d\vec{A}}{dt} = \frac{\partial \vec{A}}{\partial t} + \vec{v} \cdot \vec{\nabla} \vec{A}$ . (Hint...you don't necessarily have to use index notation here. Think of how you would define  $d\vec{A}$  in terms of partial derivatives).